



Enhancing Positioning **Resolution**

of **Elliptec Motors**

using **New** Generation **Low-Cost Sensors**

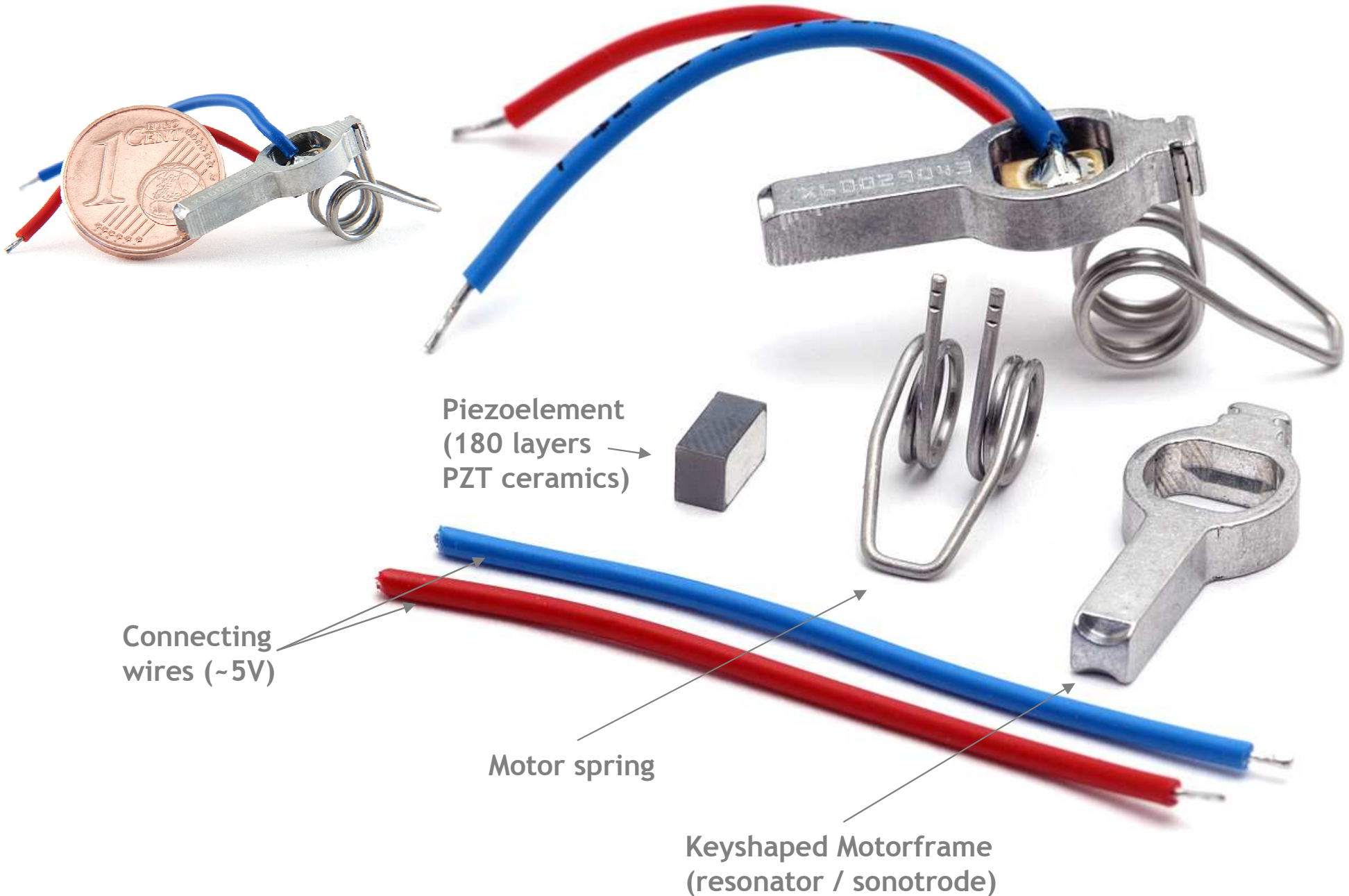
Christian Stromberg
Application Development &
Technical Support

Elliptec AG: Who we are

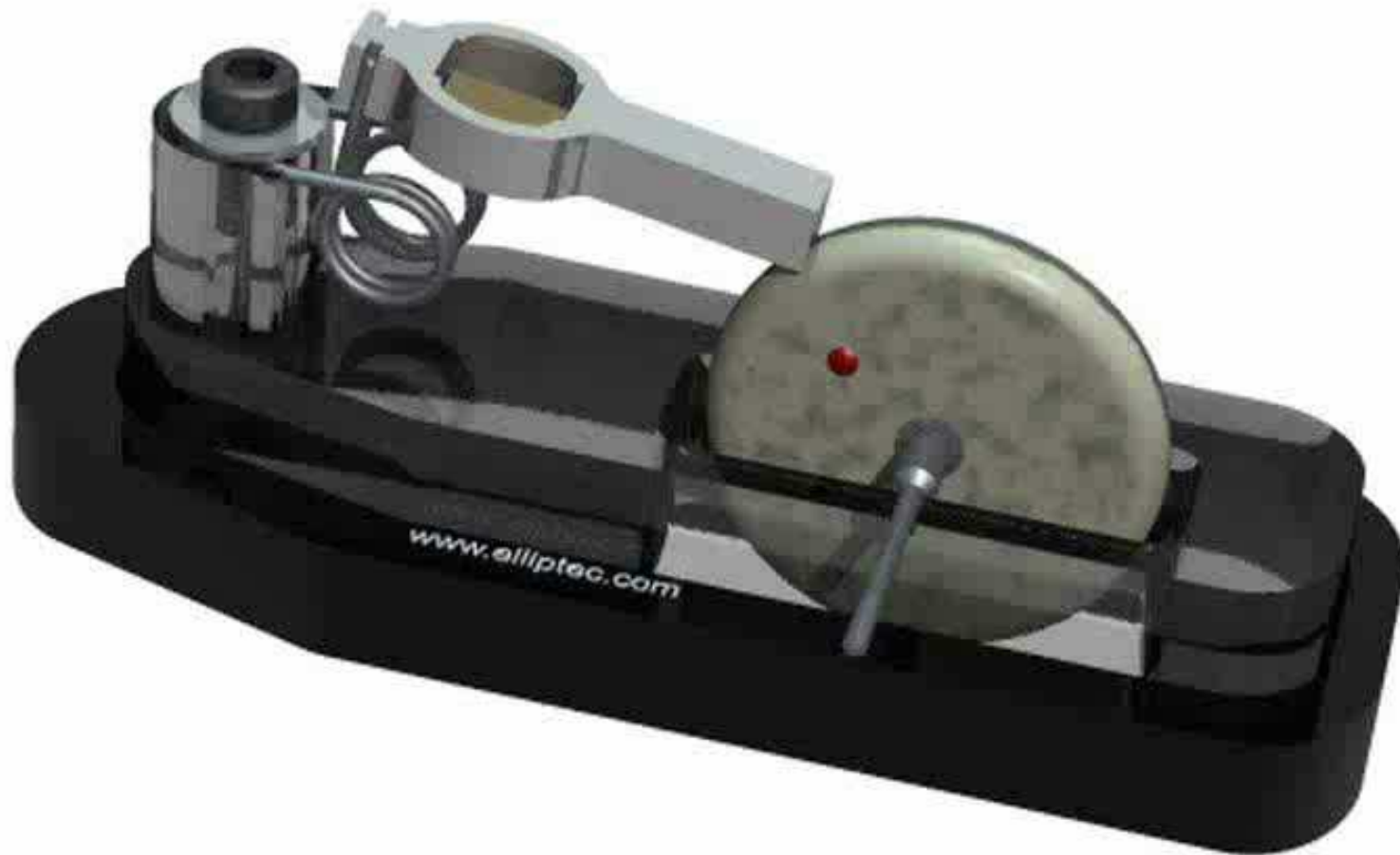
- e Elliptec develops, produces and sells **low cost piezo-motors and -actuators**
- e Elliptec offers **engineering services and design-in support** for their products
- e Headquarters and production facility is in **Dortmund, Germany**



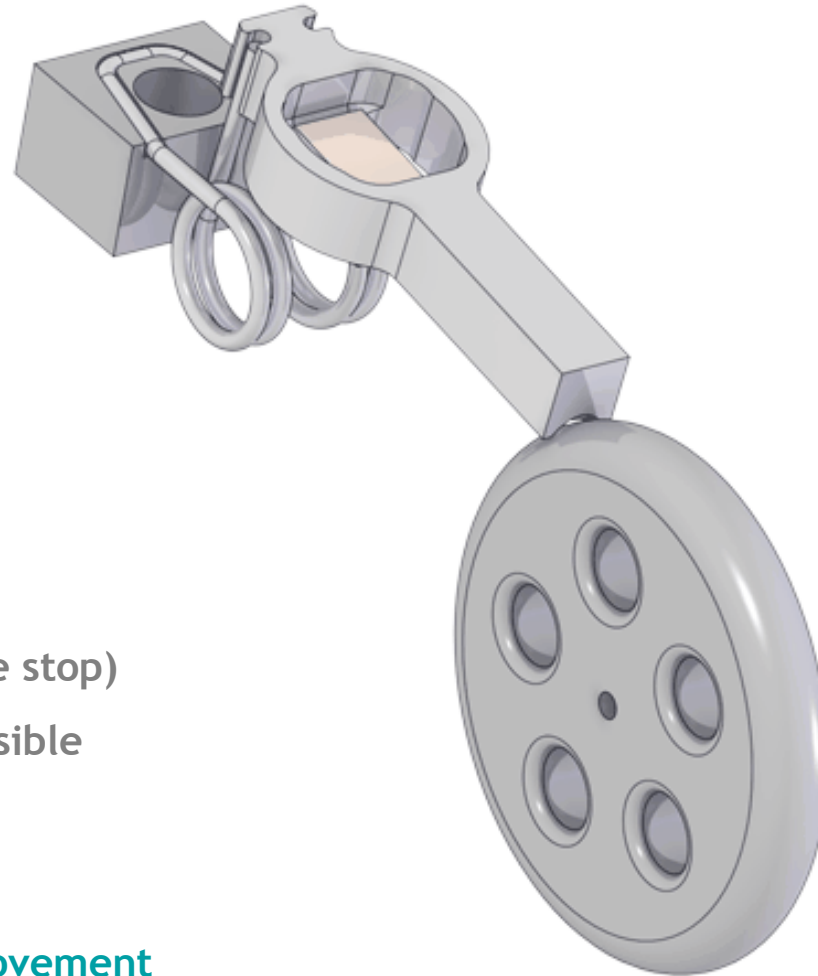
Elliptec Motor X15G - only 3 functional parts



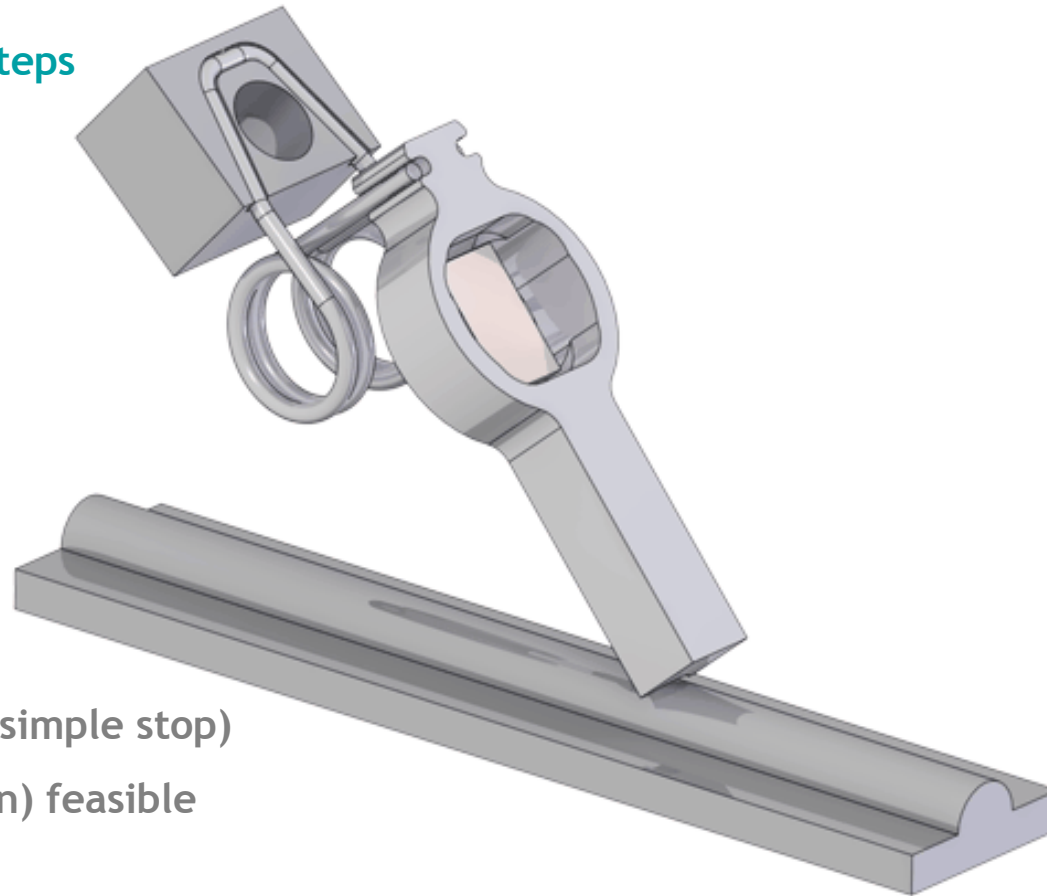
Elliptec Motor X15G - how it works



- e* Driving by **small resonant steps**
 - e* Driving by **friction**
 - e* FWD @ **80kHz**
 - e* BWD @ **100kHz**
 - e* Fast: **350mm/s !**
-
- e* Precise: **< 15 μ m** accuracy (simple stop)
 - e* Higher precision (submicron) feasible
 - e* Dynamic: start/stop **< 5ms**
 - e* **Low cost**
 - e* **Direct** linear, rotational or XY **movement**



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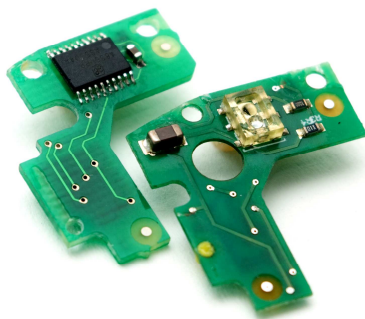
Low Cost Concept = Low Cost System



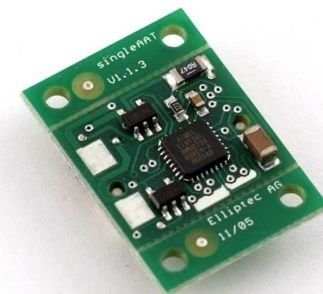
Low Cost **Concept**

means

- e** Low Cost **Motor**
- e** Low Cost **Sensor**
- e** Low Cost **Controller**



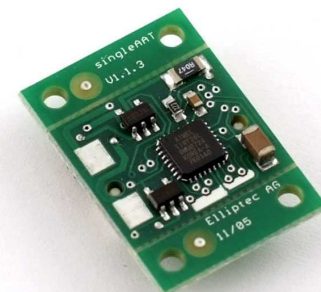
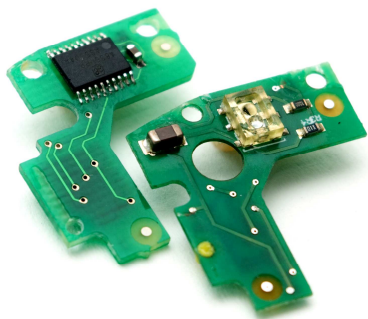
sensor requirements **vs.** controller capability



Demands - (1)



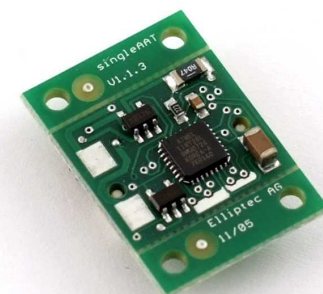
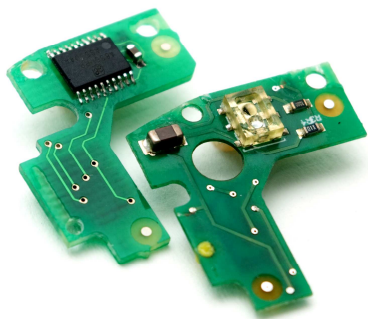
High sensor resolution
to exploit Elliptec Motor X15G
positioning capabilities



Demands - (2)



Quadrature incremental output
for simple signal processing by controller

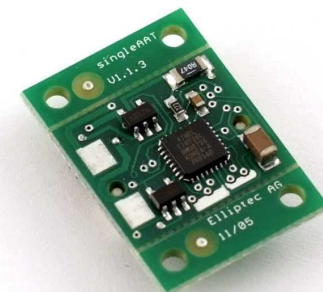
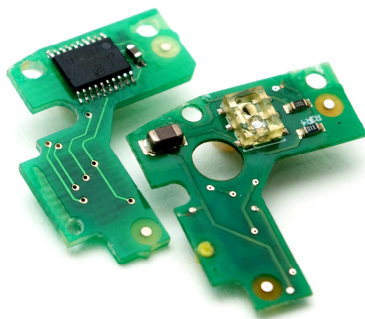


Demands - (3)



Index pulse

to allow tracking positioning signals even at high speed without high CPU load on controller

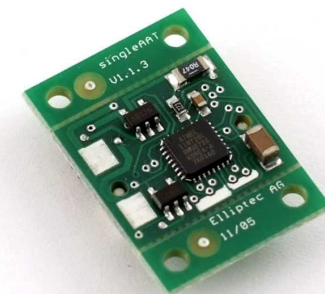
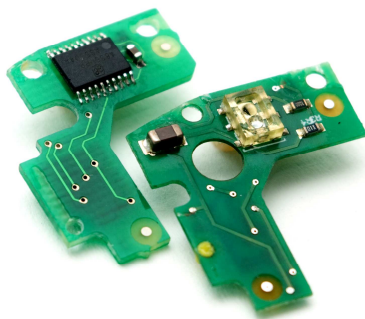


Demands - (4)



Processing Speed

to allow the use of intelligent positioning algorithms for driving the motor and to process sensor signals

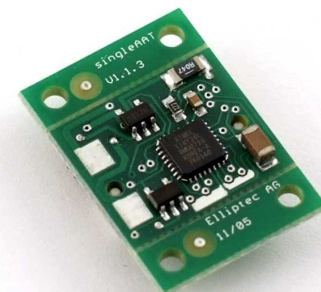
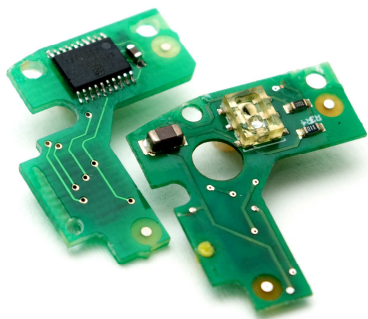


Demands - (5)



Small packaging size

to contribute to the small form factor of
Elliptec Motor X15G and Elliptec
Controller

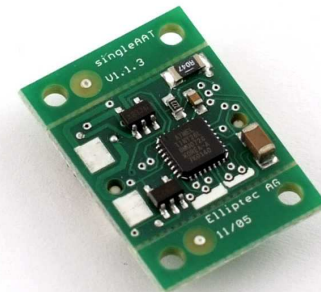
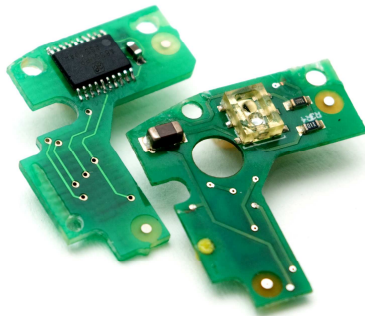


Demands - (6)

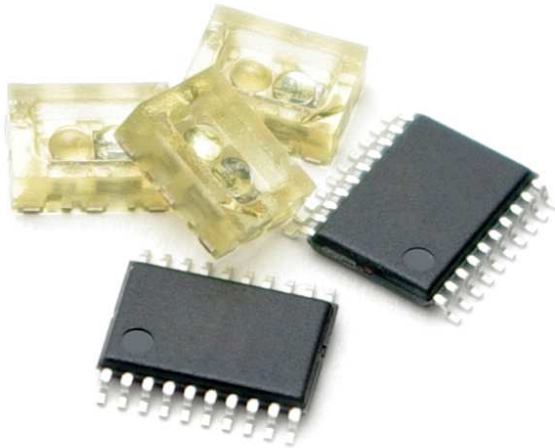


Low Cost

costs should not exceed the controller
itself



New Generation **high** precision **low** cost sensors



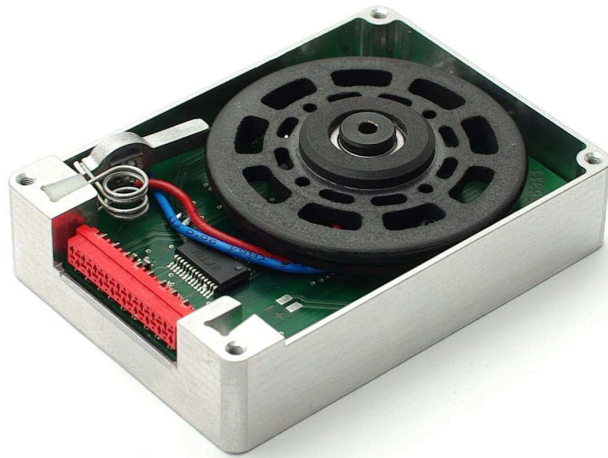
e high resolution - 0.5 μ m ✓

e quadrature output - by sensor ✓

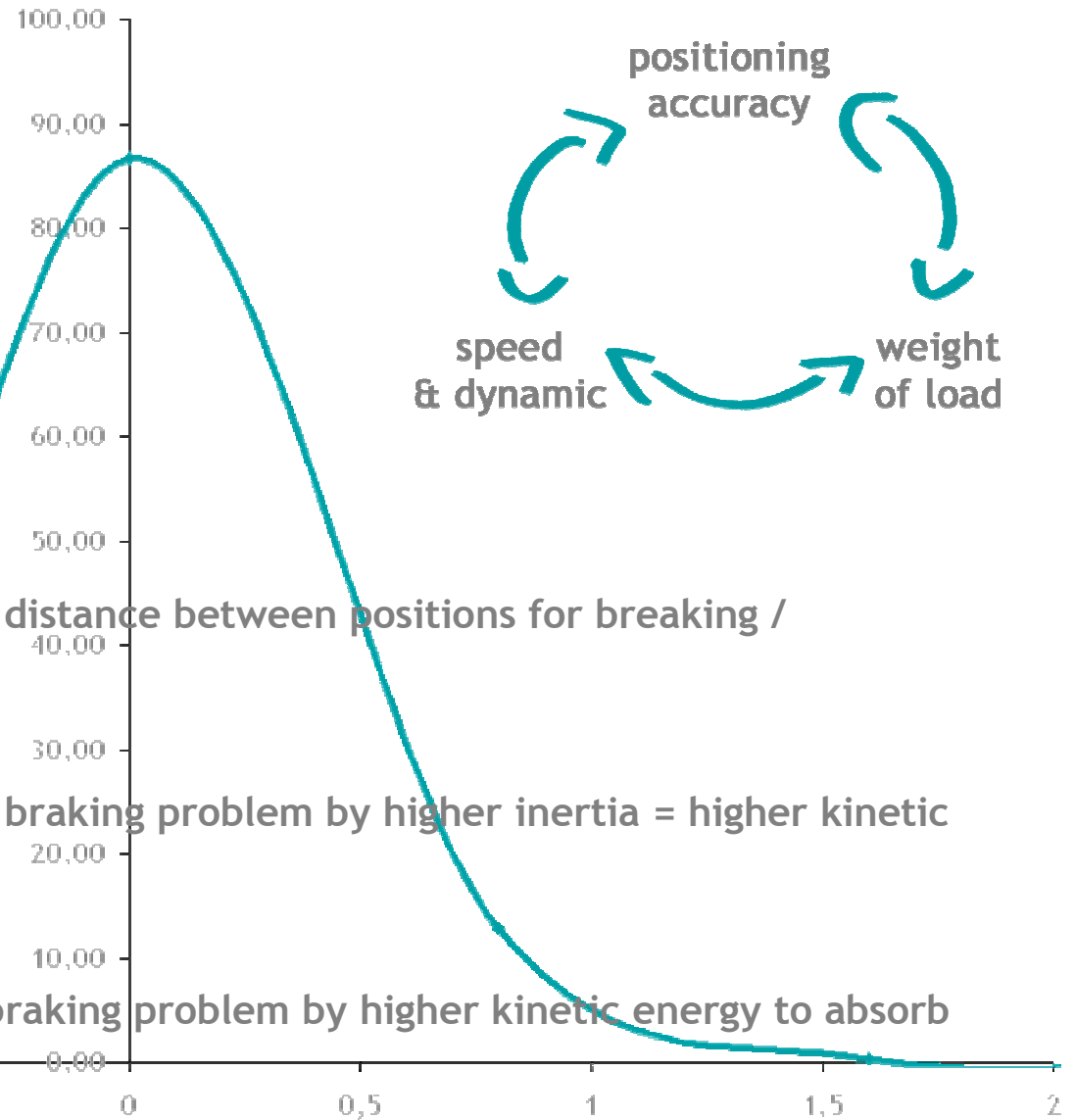
e index pulse - every 2mm ✓

e small packaging size - 7x7mm ✓

e low cost - <<10€ ✓



rel. amount of deviation [%]



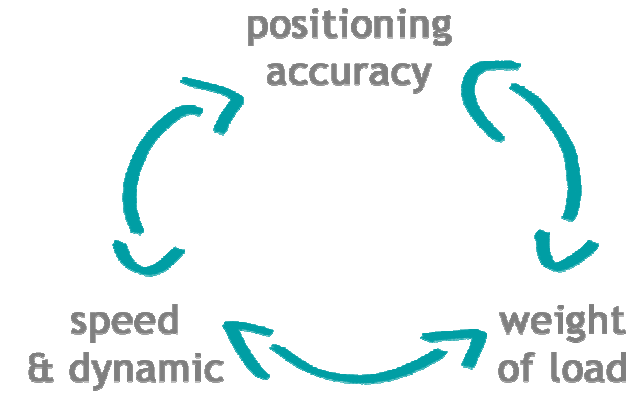
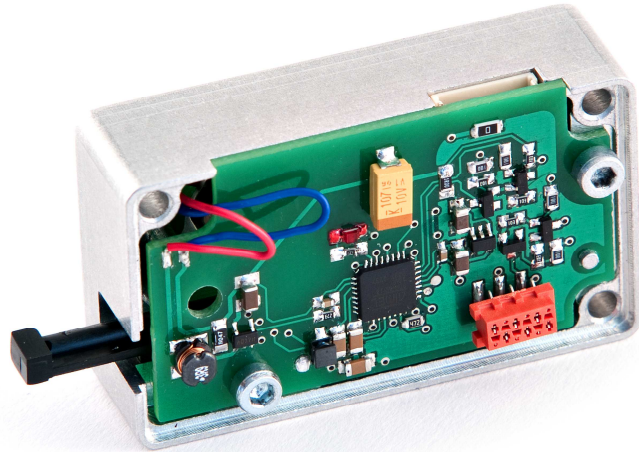
e higher resolution → shorter distance between positions for braking / compensating load inertia

e increasing load exacerbates braking problem by higher inertia = higher kinetic energy to absorb

e higher speeds exacerbates braking problem by higher kinetic energy to absorb

→ Requirements for intelligent positioning algorithms

Bringing together **sensor** and **motor** technology



e higher resolution → higher influence of mechanical tolerances

e finer steps → less friction required for smooth acceleration

→ Requirements for refined precision miniature ball bearings

Example: Algorithm Compensating Position Jitter and Overshoot

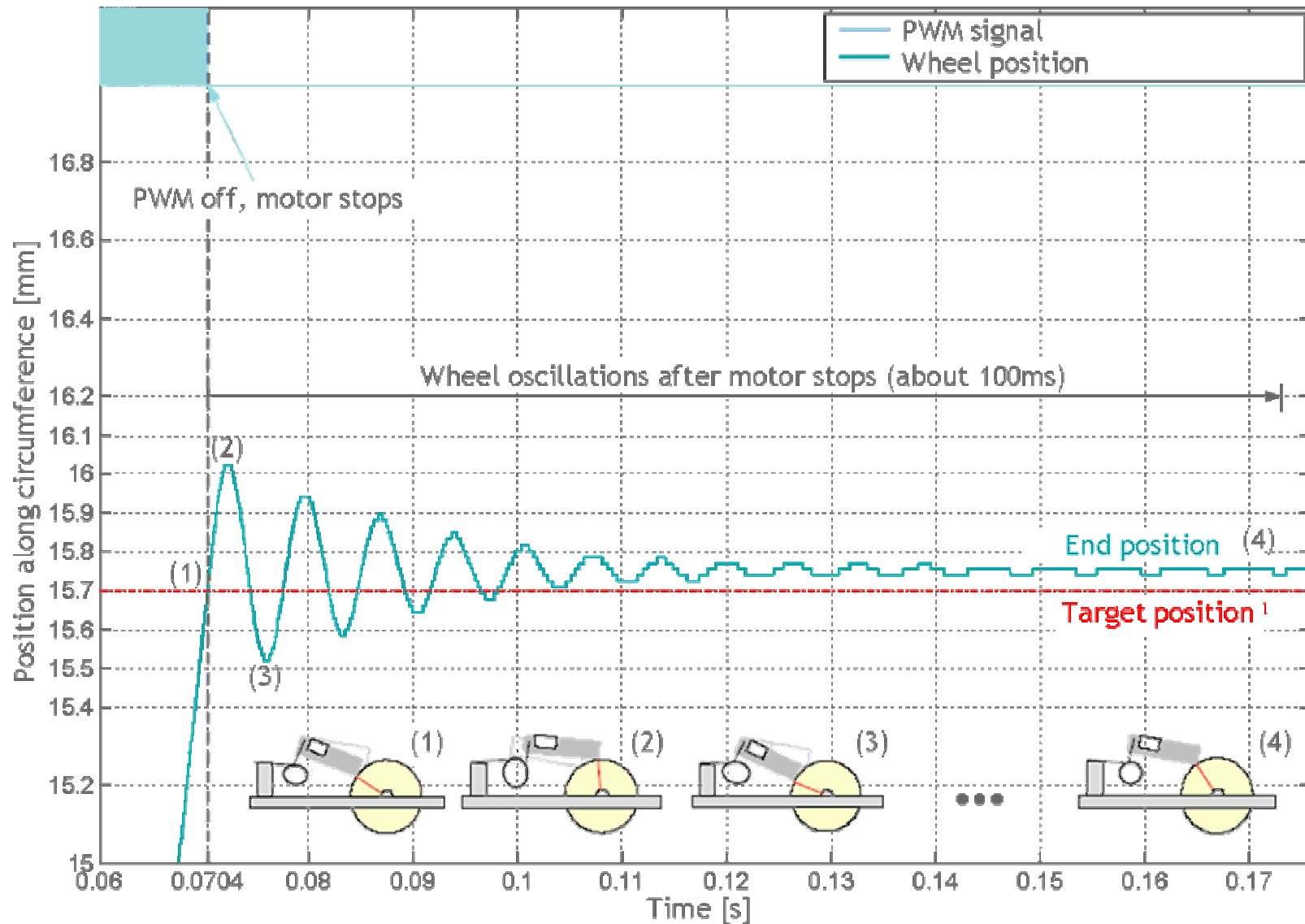


Fig. 1: Settling oscillations after the motor has been stopped in mid-operation.

Example: Algorithm

Compensating Position Jitter and Overshoot

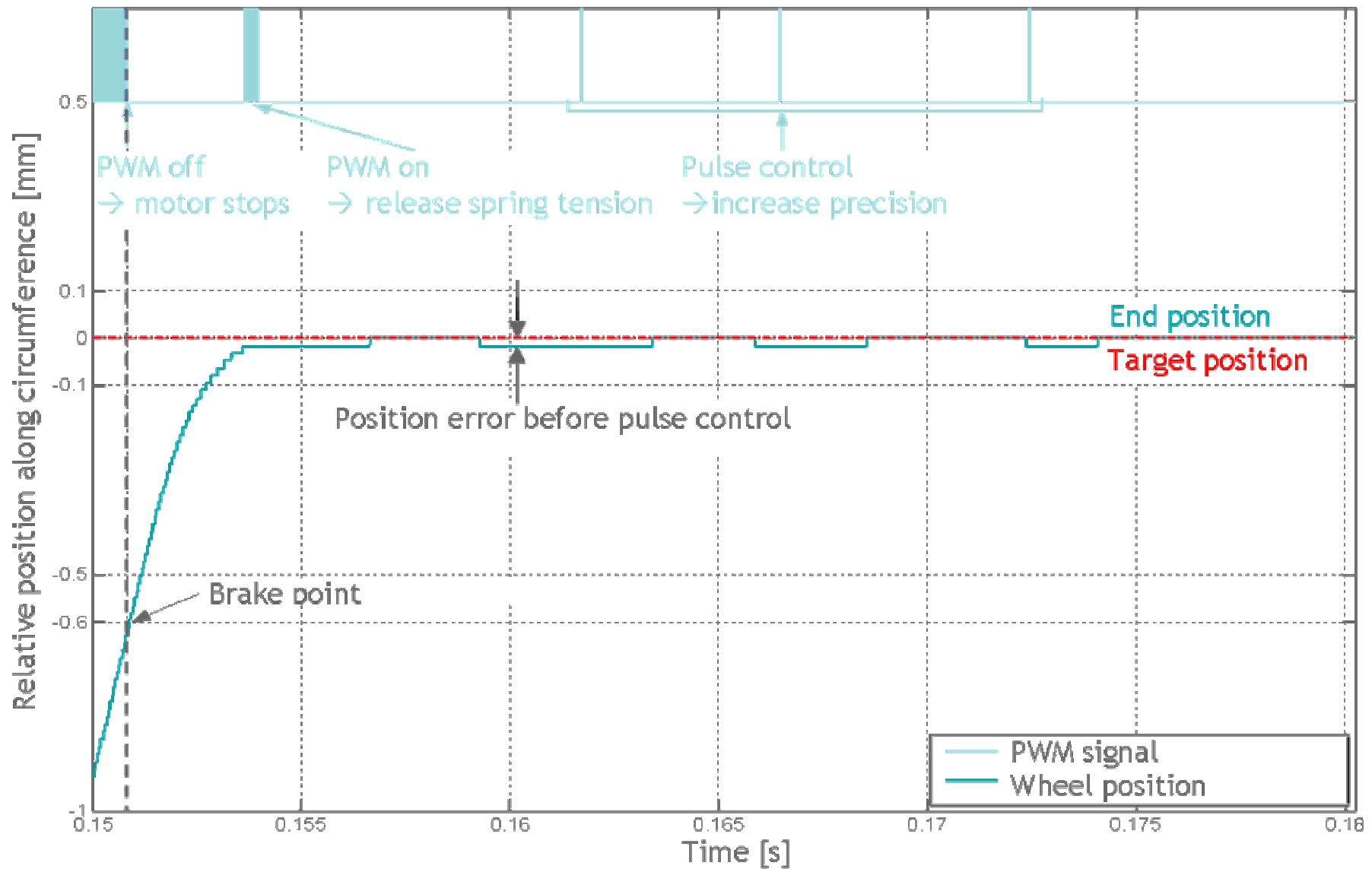
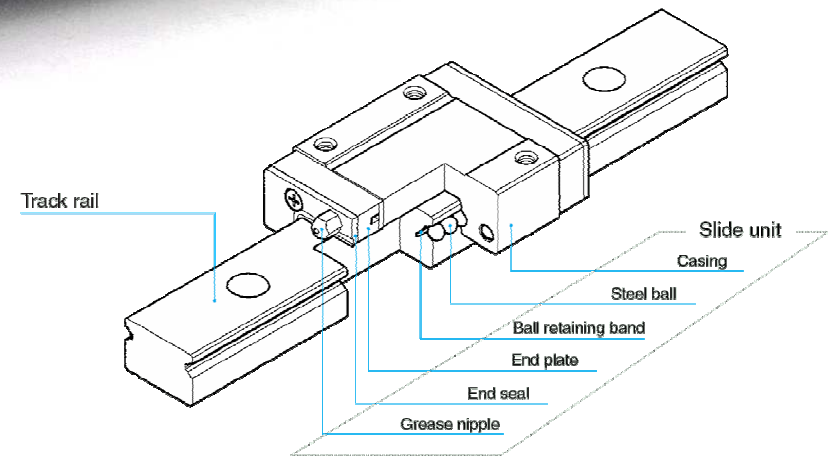


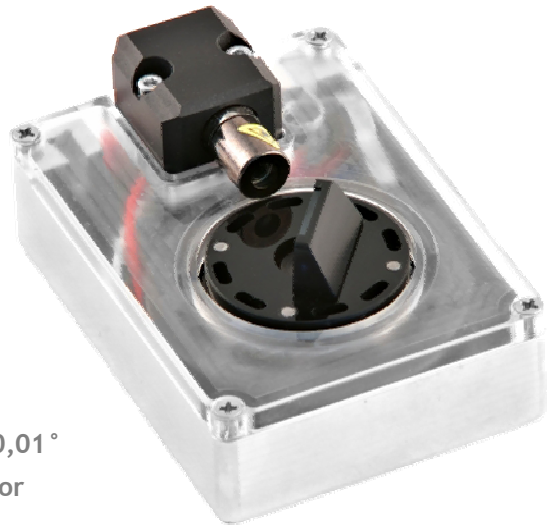
Fig. 2: Pre-compensation of settling vibrations.

Example: Bearing Low Friction and High Accuracy



- e Miniature size
- e High accuracy achieved by eliminating the number of potential errors using a simple design
- e Stainless steel with high corrosion resistance
- e Flexible assortment with extensive amount of variations for multiple purposes
- e “Ball retained”-types available even in miniature sizes

Result: New Elliptec Standard Products



R2K Module

resolution: < 0,01°
magnetic sensor
USB interface
R2K-001

Symbol	Parameter	Ratings			Unit
		min.	typ.	max.	
Vcc	Supply Voltage for Powerstage	4,5	5	5,5	V
M _H	Unpowered Holding Torque	10	16	20	mNm
	Supply Current @ maximum Speed		450	600	mA
I _{cc}	Supply Current during Calibration			900	mA
	Supply Current in Idle Mode			60	mA
T _{ambient}	Operating Temperature	-10	20	65	°C
j	Angular Resolution		-0.01		°



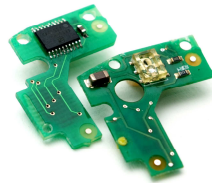
L2K Modul

resolution: <1 μm
magnetic sensor
USB interface
L2K-001

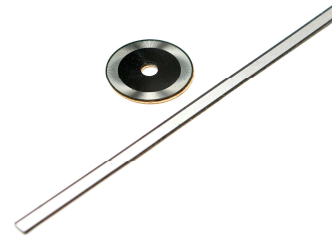
Symbol	Parameter	Ratings			Unit
		min.	typ.	max.	
Vcc	Supply Voltage for Powerstage	4,5	5	5,5	V
F _H	Unpowered Holding Force	0,5	0,8	1,2	mN
v ₀	No-Load Speed	200	300	450	mm/s
F _B	Maximum Blocking Force	200	300	500	mN
F ₀	Motor Driving Force	100	200	300	mN
	Supply Current @ maximum Speed		450	600	mA
I _{cc}	Supply Current during Calibration			900	mA
	Supply Current in Idle Mode			60	mA
I _{motor}	Peak Current			1,5	A
T _{ambient}	Operating Temperature	-10	20	65	°C
n	Linear Resolution		0,48		μm°
H	Linear Stroke		20		mm

Application Development: Product Portfolio

Adopted sensors & linear guides



sensor integration
 optical:
 Resolution 30 μ m
 magnetic:
 Resolution 0,48 μ m



encoder strip
 Rotary: (\varnothing 16mm, 300 lines)
 Linear: (200mm, 2500 lines)



precise linear guide with ball bearing
 various sizes, eg. 25mm



simple linear guide
 length: 36mm

Wheels and other driven geometries



wheels
 diameter: 20mm
 diameter: 14mm

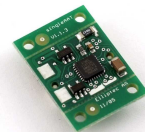


wheel segments
 radius: 5mm
 radius: 8.5mm
 radius: 14.5mm



R40 accessories
 knop, mirror, axis

Motioncontrollers



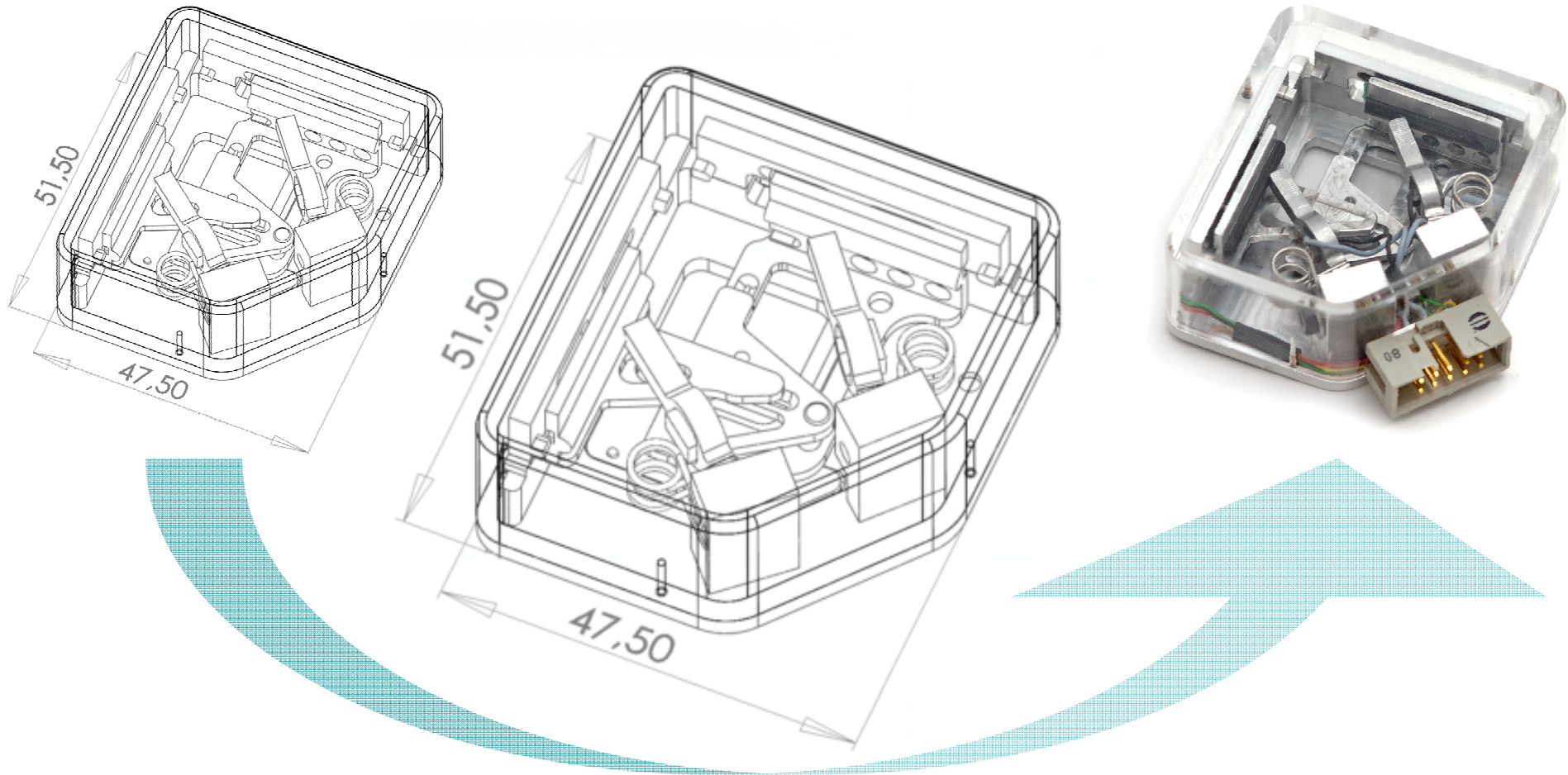
Elliptec Controller
 std. control unit



1-motor-controller
 with USB Interface
 remote accessible via command set



2-motor-controller
 with USB Interface
 remote accessible via command set



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